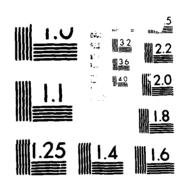
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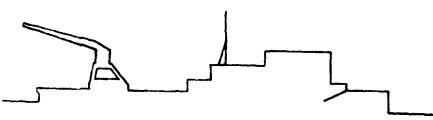
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ST. CROIX MOORING DESIGN

by

William N. Seelig

FPO-1-84 (47) December 1984



## Ocean Engineering

CHESAPEAKE DIVISION
NAVAL FACILITIES ENGINEERING COMMAND
WASHINGTON NAVY YARD
WASHINGTON, DC 20374

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ST. CROIX MOORING DESIGN

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APPROVED BY:

SHUN C. LING P.E.

Director

Engineering Analyses Division

OCEAN ENGINEERING & CONSTRUCTION PROJECT OFFICE CHESAPEAKE DIVISION
NAVAL FACILITIES ENGINEERING COMMAND
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1. The mooring will accommodate large submarines ("Lafayette" SSBN 616 or smaller) and a wide variety of surface ships ("Spruance" DD 963 was selected as typical). These vessels have the following characteristics:

Ship Class	Ship Length (ft)	<pre>Max. Nav. Draft   (ft)</pre>	Mooring Swing Circle (ft)
DD 963 "Spruance"	564.	30.	750.
SSBN 616 "Lafayette"	421.	32.	560.

- 2. Both static and dynamic ship/mooring forces and interactions are considered and a Class A mooring with 100 kips working holding capacity was selected. This corresponds to a maximum 2.0 knots current with a simultaneous 50 knot, 30-second duration wind. The surface ships control the design forces. The buoy is to be located 500 yards north of the pier in a water depth of 60 feet.
- 3. Because of the great uncertainty in bottom conditions the mooring will be installed and tested and the rating of the mooring will be re-evaluated.
- 4. A site survey is planned in January 1985. Design adjustment may be made based on those survey results and/or installation experiences. Drag anchors as well as Propellment Embedment Anchors will be mobilized to cover installation contigencies.

#### St. Croix Mooring Design

#### EXECUTIVE SUMMARY

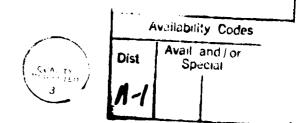
This report presents the design of a mooring to service surface ships and submarines operating off the west coast of the island of St. Croix. West Indies. This emergency mooring is required because the nearby Frederiksted Pier was damaged during tropical storm "Klause" on 1 November 1984.

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#### DESIGN OF THE ST. CROIX MOORING

by

William N. Seelig, P.E.

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**FIGURES** 

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- A. FORCE CALCULATION FOR SSBN 616
- B. FORCE CALCULATIONS FOR DD 963
- C. BUOY SURVIVABILITY
- D. CATHODIC PROTECTION FOR CHAIN

#### DESIGN OF THE ST. CROIX MOORING

by

William N. Seelig, P.E.

#### INTRODUCTION

The purpose of this mooring is to service submarines and surface vessels operating off the western coast of St. Croix, West Indies. The mooring is needed because the Frederiksted Pier was damaged in a storm (Figure 1).

The approach taken in this design is to custom design a mooring for the site using mostly standard materials available in U. S. Navy Fleet Mooring Inventory. Both static and dynamic behavior of ships in the mooring are considered. Propellment Embedment Anchors (PEA) are specified as the primary anchor type, due to the poor bottom conditions in the area. A "soft" buoy and protective collar around the chain riser are used to protect contact with a submarine coming close to the mooring. A sinker and three ground legs are used to provide dynamic energy absorption in the mooring.

#### DESIGN CONDITIONS

- 1. <u>Vessels</u>. It is not known exactly what vessels may use the mooring, so the design is tailored to service all submarines of "Lafayette Class" (SSBN 616) and smaller. The "Spruance Class" DD 963 was taken as representative of U. S. NAVY surface combatants. A list of vessels authorized to use the mooring will be made once the mooring is installed, tested and rated.
- 2. Environment. A 50.0 knot wind with a 30-second duration was selected for design based on engineering judgement. Note that this operational wind speed may have to be adjusted based on the rating assigned to the as-built mooring.
- 3. <u>Tide.</u> The normal tide range at the site is 0.8 feet with an extreme tide range of 1.8 feet.
- 4. <u>Currents</u>. Little is known about the currents in the area. Howard Kelly (LANTDIV, phonecon of 12/10/84) states that current speed varies with location, but could be up to 2 knots. A design current of 2.0 knots is therefore specified. More information on currents should become available as a result of a planned site survey and based on observations made during mooring installation.

- 5. <u>Bathremety Data.</u> Chart Number 25644 (May 1975) and NOAA survey files (personnel communication, National Ocean Survey) provided water depth and bottom conditions data. National Ocean Survey study of the area shows that the bottom is a combination of coral and sand (Figure 2).
- 6. Additional Data. An Underwater Construction Team One (UCT-1) is being planned for January 1985 which should provide additional information on bottom type, sediment thickness, bottom slope, water depths and current speeds.

#### DESIGN FORCES

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The mooring design is based on static and dynamic design forces. A ship in a mooring may have much different motions than an unmoored vessel at the same site. This dynamic behavior depends on characteristics of the mooring and ship. Therefore, an iterative design procedure was used and many alternative designs considered. Only the selected design is presented in this report.

#### 1. STATIC FORCES.

Methods in Design Manual 26.5 "Fleet Mooring" (95% Submittal) were used to calculate static mooring forces. In this method the design current speed of 2.0 knots was used. Thirty second wind speeds of both 35 and 50 knots were used to obtain data on the sensitivity of forces on wind speeds. Calculation in Appendicies A and B were then used, together with a computer program, to find the equilibrium position of the vessel (Figure 3). Once the equilibrium position is known the required static mooring hawser tension (Figure 3) is also calculated using the computer program. Calculation procedures are described in great detail in DM 26.5, so they are not repeated here.

Little is known about the direction of currents and winds at the design site. Therefore, the approach taken here was to assume that the winds and currents could come from any direction. Relative wind/current directions at 10 degree angle increments were all analyzed and the combination of directions that gave the highest mooring force were selected for design. These static design equilibrium forces are given in Table 1.

#### 2. SHIP DYNAMICS - YAW.

Even in relatively steady wind and current conditions a vessel moored to a single point mooring may experience dynamic action. Many references document this "fish-tailing" illustrated in Figure 4 (see Chrenshaw, R. S., Naval Shiphandling, Naval Institute Press, Annapolis, Md., 1975). "Fish-tailing" occurs because the total moment curve of the ship in the mooring may have a flat slope near the "equilibrium" position. Even a very small pertubation in forcing causes the ship to yaw from equilibrium (Figure 5). inertia together with the flat sloped moment curve means that the ship may have +/-20 degree of yaw from equilibrium before the ship is brought back towards equilibrium. The main consequence of this yawing action is that mooring hawser forces are greatly increased. For example, the DD 963 calculations shown in Figure 5 indicate a 42 kip static mooring load at equilibrium that jumps to 96 kips at +/-20 degrees yaw (wind and current azimuth both 270 degrees for the example shown). Design forces including the +/-20 degree yaw are shown in Table 1 for the DD 963. Values at +/-10 degree yaw are used for the SSBN 616 (Figure 6 and Table 1). The smaller value of yaw for the submarine is justified based on the fact that the total restoring moment on a SSBN 616 is higher than for a DD 963.

#### 3. DYNAMIC FORCES - SURGE.

A ship may also surge while in a mooring. Surge may be especially important, even if it is small, because (a) moorings may be highly non-linear and a small change in ship deflection away from the ground ring will produce a large increase in mooring force and (b) the ship and mooring (if poorly designed) may get into a resonance condition where motions and forces can be amplified.

Surge dynamics are investigated in this report by use of a one-dimensional computer program that simulates important aspects of the mooring, ship and forcing. Details of this numerical model are too complex to present here. The following gives a summary of important computer program components:

a. The mooring is represented by the non-linear load/deflection curves shown in Figure 7. Deflection (surge) of the bow of the ship away from the ground ring is shown on the x-axis and restoring force in the mooring shown on the y-axis. The load/deflection curve includes non-linear stretch of the mooring hawser (if any), submergence and rotation of the buoy, displacement of the riser catenary, lifting of the sinker, lifting and the catenary of ground legs.

- b. The forcing wind is generated by the computer using the wind spectrum presented in Vellozzi, J. et al, "Gust Response Factors", ASCE, Structural Division, June 1968, pp. 1295-1313. This generalized wind spectral shape was developed by analyzing records from 90 storms under a wide variety of conditions. The computer takes the spectrum, uses wind energy components with periods between 5 seconds and one hour and generates the instantaneous wind acting on the vessel at one second intervals. A sample wind time history is given in Figure 8.
- c. Hydraulic forcing on the vessel includes a steady current and reversing current component due to long waves.
- d. Ship response/forcing includes: ship mass; added mass; damping; non-linear wind forcing; non-linear current forcing including the effects of the ship motion; and non-linear restoring forcing of the mooring. The solution is a time-marching scheme that updates the forcing and ship conditions at one-second intervals. Conditions are modeled for 1000 seconds and the highest predicted mooring hawser tension reported.

Sample computer plots of mooring hawser tension are given in Figure 9 (DD 963) and Figure 10 (SSBN 616). The destroyer is predicted to experience significant dynamics during a storm, while the submarine remains relatively static. These and many other computer plots show that the ship/mooring combination is well matched and that yaw action produces the highest total mooring force (Table 1).

#### MOORING DESIGN

The selected mooring design (Figure 11) was evolved after considering many factors:

- a. A Class "A" mooring with 100 kips restoring force is desirable.
- b. The SEACON will be used for installation.
- c. The SEACON can easily mobilize any materials from the inventory of Fleet Mooring Materials in San Diego.
- d. Installation is planned for early 1985.
- e. The mooring will be used for surface ships, which require moorings with good energy absorption characteristics.
- f. Submarines will use the mooring, therefore the buoy should be soft and the riser chain will be protected to minimize the possibility of metal contact with the submarine.
- g. Propellant Embedment Anchors are used as the best and most cost effective method of providing anchoring considering the bottom type. However, since bottom conditions are poorly known, Stockless Anchors will also be mobilized as a continency.

Predicted characteristics of the mooring with some notes are shown in Figure 12. Note that the energy absorption characteristics of the mooring are good throughout the working range of the mooring.

Materials to be mobilized for this mooring are given in Table 2. This list includes some spare materials. Cathodic protection for the chain is illustrated in Appendix D. Three 20-kip Stockless Anchors are also specified. These anchors could be used in various combination, if one or more of the PEA placements are unsuccessful. Another advantage of mobilizing these anchors is that they are needed for other projects on the U. S. East Coast, if the PEA's are successful.

#### MOORING LOCATION

A study of the required swing circles (Table 3), required water depths, bottom slopes and use of the mooring suggests that the site shown in Figure 13 is by far the best location for the mooring. Figure 14 shows the ships in the mooring at scale with the ship perpendicular to shore.

#### INSTALLATION SEQUENCE

D

The following general installation sequence is recommended. More detailed installation plans will be formulated by the FPO-1 Construction Division as the project progresses.

- 1. Mobilize to the site with materials.
- 2. Locate the mooring site.
- 3. Locate the exact position of two of the PEA's.
- 4. Install, set and test the two PEA's.
- 5. Attach one ground leg to each of the two PEA's, attach riser, buoy, sinker and ground ring. Also attach the third ground leg.
- 6. Put the mooring in the water.
- 7. Tighten the mooring by pulling the mooring towards the third anchor site.
- 8. Locate, install and test the third PEA.
- 9. Attach the third PEA.

#### SUMMARY

A mooring design is presented for western St. Croix to service submarines and surface ships. Mooring use, performance characteristics, environmental conditions, the site, installation equipment and available Fleet Mooring Inventory materials were all considered in formulating the design.

Unique features of this mooring are that a "Soft" mooring buoy and covering riser chain are provided to minimize the possibility of damage to a moored submarine.

This mooring should be installed and each anchor leg tested. At that time the capacity and use of the mooring will have to be re-evaluated. This procedure is recommended due to the uncertain conditions at the site.

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Conclusion: The LPD-4 could only use the az-designed mooning in relatively calm conditions.

#### Table 1. DESIGN FORCES

## 30-second duration design wind speed = 50 knots design current speed = 2.0 knots\*

### Design Load Between Ship & Mooring (Kips)

<u>Condition</u>	"Spruance" DD 963 L = 564 ft	"Lafayette" SSBN 616 L = 421 ft
Static Equilibrium	42	7.5
Static + Dynamic Yaw	100 (+/-20 deg)	3l (+/-10 deg)
Static + Dynamic Surge	56	8.2

<sup>\*</sup>Relative direction between wind and current selected for each case to give the highest load.

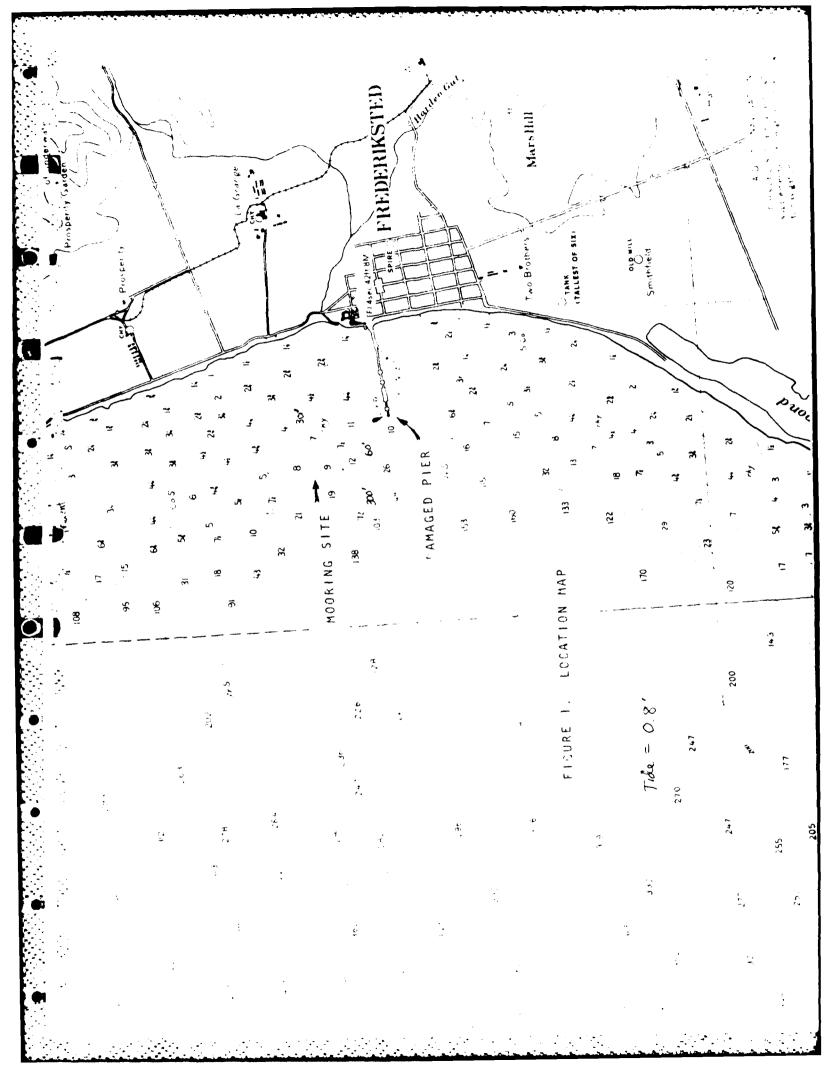
Table 2. Mooring Materials to Mobilize to the Site

Item	Total Number (including spares)
2 1/4" Chain	13 shots (or 12 shots + short sections)
2 1/4" Shackles	6
2 1/4" Detachable Links	17
2 1/4" Anchor Joining Links	10
2 1/2" Anchor Joining Links	3
2 1/4" Size Ground Ring	1
2 1/4" Sinker Shackle	3
16 Kip Stockless Anchor	1
20 Kip Stockless Anchor	3
100 Kip PEA Package	4
20 Kip Reserve Buoyancy Buoy (soft type)	1
2 1/4" Pelican Hooks	2
Chain Cathodic Protection Assembl	lies 10
2 1/4" Pear Links	4
Tires	As Needed

IJ

Table 3. Ship/Mooring Characteristics

Ship Class	Ship Length (ft)	Approx. Hawser Length (ft)	Max. Nav. Draft (ft)	Mooring Swing Circle
"Spruance" DD 963	564.	150.	30.	750.
"Lafayette"	421.	100.	32.	560.



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CHESAPEAKE DIVISION PROJECT: St. Croix Mooring **Naval Facilities Engineering Command** NDW Station: \_\_\_\_\_ DISCIPLINE E S R: \_\_\_\_\_ Contract: date: 12/14/8 Calcs made by: \_\_ W. SEELIG Ship in Mooring Calculations for: Calcs ck'd by: date: EQUILIBRIUM C.G. C.G.(BEFORE (AFTER LOADING) LOADING) EQUILIBRIUM POSITION (AFTER LOADING) POSITION BEFORE LOADING Figure 3. SHIP IN A SINGLE POINT MOORING

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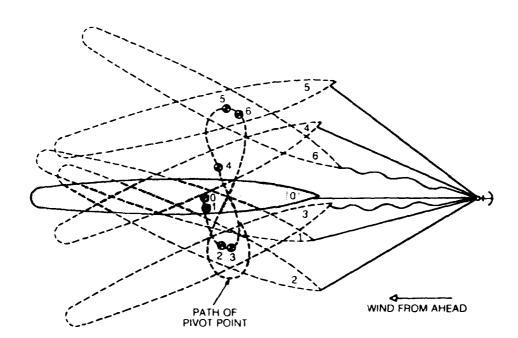
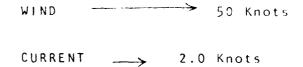


FIGURE 4. A SHIP FISH TAILING IN A SINGLE POINT MOORING

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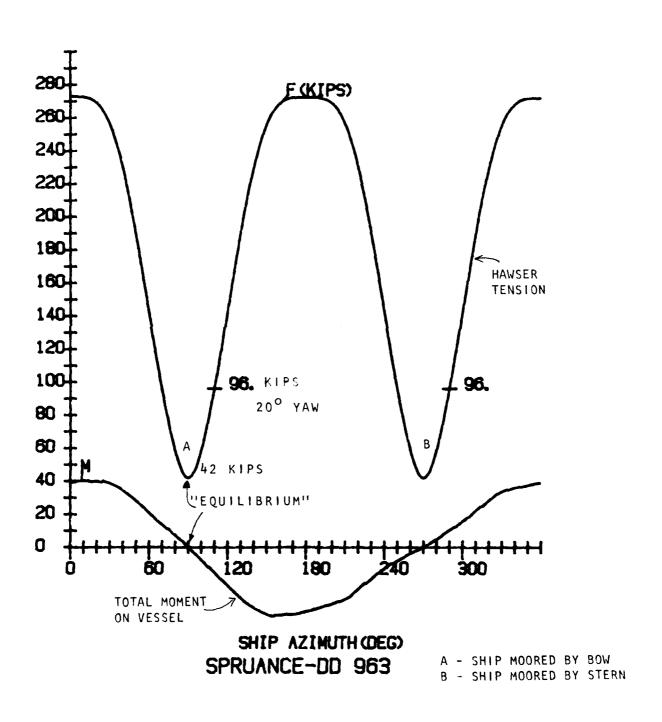
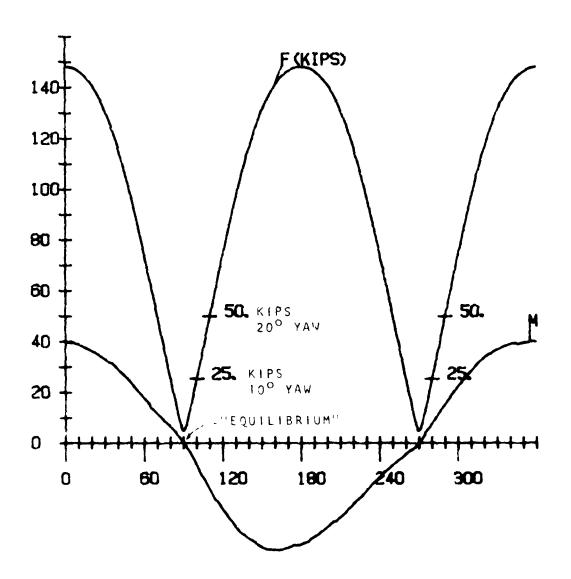


FIGURE 5. MOORING HAWSER TENSION FOR A DD 963
AT A SINGLE POINT MOOR UNDER
"EQUILIBRIUM" AND VARIOUS AMOUNTS OF YAW

WIND \_\_\_\_\_ 50 Knots

CURRENT -> 2.0 Knots

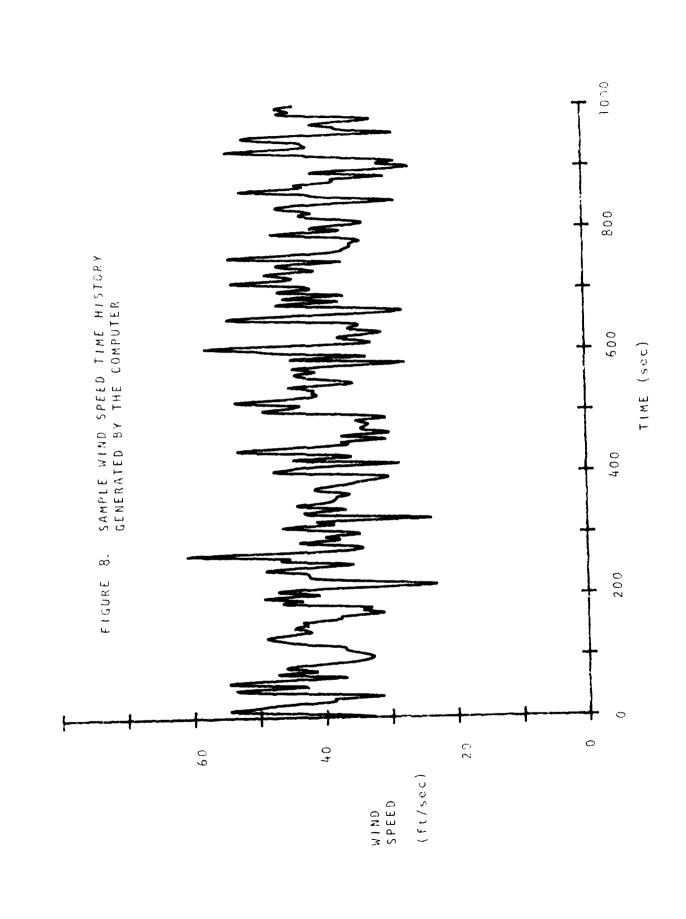


SHIP AZIMUTH (DEG)

LAFAYETTE - SSBN 616

FIGURE 6. MOORING HAWSER TENSION FOR A SSBN 616 AT A SINGLE POINT MOOR UNDER "EQUILIBRIUM" AND VARIOUS AMOUNTS OF YAW

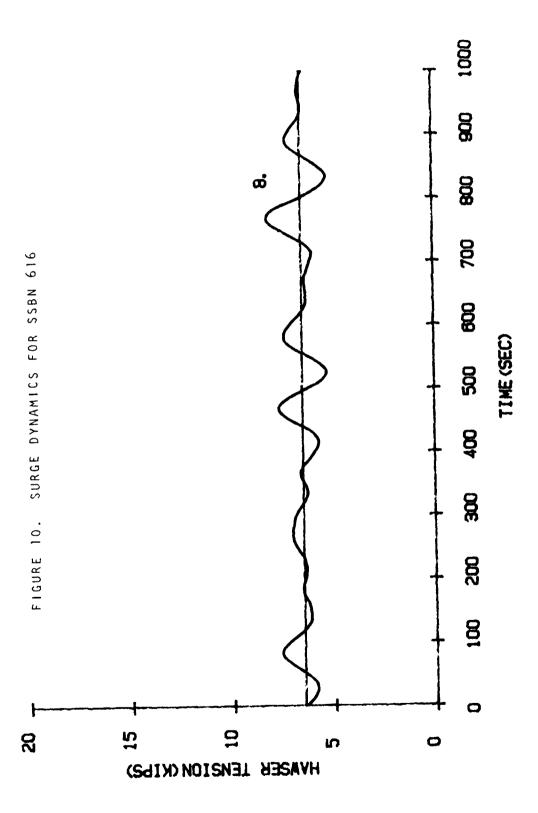
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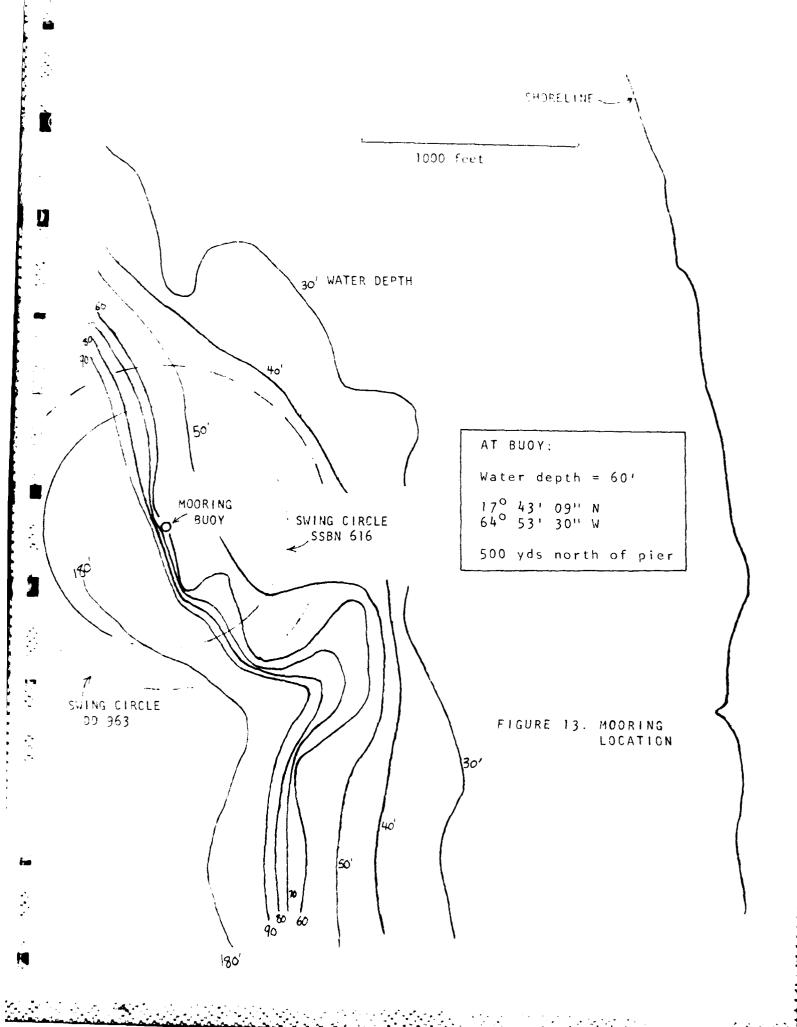


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16 UNC 5/8"	GALVANIZED LOCK WASHERS	AS REQUIRED	GALVANIZED STEEL	SEE DETAIL A
17 UNC 578" 11	GALVANIZED HEX NUTS	AS REQUIRED	GALVANIZED STEEL	
	Figure 11. MOORING DESIGN	UN		© 9 LINKS
(E)	(g) (D) (Q) (Q) (Q) (Q) (Q) (Q) (Q) (Q) (Q) (Q	0	(c)	
	- C			
	SEE NOTE 8 ONE PER	GROUND LEG (3 REQ'D)	, EG	C STON STON
NAFEC DRAWING M	Shot of chair		ם ק	

NAPPAC DRAWING "3026350

CHESAPEAKE DIVISION PROJECT: **Naval Facilities Engineering Command** NDW Station: \_\_\_\_\_ DISCIPLINE E S R: \_\_\_\_\_ date: Calcs made by: \_ Calculations for: Calcs ck'd by: \_ date: 100-Surface ship in the mooring HORIZONTAL LOAD, H (kips) Fred San 600 40 -Eng: 1.112 Contract. 20 Mich ON 3191m 5,000 200 10 20 DEFLECTION, d (ft.) page.

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CHESAPEAKE DIVISION Naval Facilities Engineering Command NDW DISCIPLINE	Station: Contract:
Calcs made by: <u>W. Seelig</u> date: <u>12/14/84</u> Calcs ck'd by: date:	- Calculations for: Ships in Marine
DD 963	<b>*</b>
	To a second seco
8 8	(A)
SSBN 616	
5	
FIGURE 14. PROFILE VIEW OF TYP	ICAL SHIPS IN THE MOORING
	page of

GPU 888-683

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#### APPENDIX A. FORCE CALCULATIONS FOR SSBN 616

DM - 26.5 "Fleet Moorings" is used in this appendix to calculate forces and moments due to wind and currents on a "Lafayette" Class submarine. Here force and moment calculations are made only in dimensionless form. A computer program is then used to make detailed calculations and to determine the corrosponding mooring forces. The approach taken in this appendix is to directly quote and use equations in the DM. DM 26.5 (95%) can be referenced for a detailed description of equations and variables.

CHESAPEAKE DIVISION Naval Facilities Engineering Command NDW	PROJECT: // // // Station:
DISCIPLINE	E C D: Contract:
Calcs made by: W. Corrig date: 12/13/8:4 Calcs ck'd by: date:	Calculations for: SEN - 6/6
Laloyette" SSBN 616	
$L = 421'$ $B = 33'$ $T = 25.2'$ (32' Max r $Disy = 6920$ LT. $A_{sike} = 4870$ ft $A_{end} = 430$ ft	navigational) 1/2 STORES
Later & Wind Look	ca. Trideat
En (S-11) Fyw= = (1,00237) Vw	$^{2}$ (0.75) $f_{yw}(0) \times 4870$ $^{3}$ $f_{4}(5.15)$
= 4,33 V~2 fyn	,(8)
Longitudian Wind Look	
F; (5-16) Fxw = 5(.00227)	12 (430) 0.4 fx, (8) =
= 0.2c Vw3	fxw(G)

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page \_\_

CHESAPEAKE DIVISION Naval Facilities Engineering Command NDW		PROJECT: Station:	
DISCIPLINE Polog mode by:	J.A.,		Contract:
Calcs made by: Calcs ck'd by:	date:	Calculations for:	Lainjette
Jaics CR U Dy.	vate		
Wind Your Mome	$\mathcal{A}$		
	1 /	> 1/3/1/0m >/	
Fg (5-29) M	xyw= = (1,002)	1) VW (4770)(	· •
			(Figsz
	= 2430	Ma Cxxm(0)	, . <sub>J</sub> = -
1.1.		, ,	
Lateral Current	COAL		
let wd = 75	1		·
(r 27) d = 27	(100h) /421-	1000 0 C 2	19
$(S-37)  \phi = 35$	(0720)/ TCIX	(3) \ (3, \ = 0	), o
Del Cm ~ 1.0			
Then (	= \$/cm = 0	.69	
L/R= 4	-21/32 =	12.76	
C 1 15	= ^ (6 ( 4	21)/525.2 =	. 679
CPCZV	7 = 0.07(7	21)/ 0 < 5, 2 = =	5/.1
From Fig	58 K=1,2		
از ا	58 K=1,2 57 Cycli= 56 Cyclo=	3,6	
Fig	26 Chepo=	13 (75	/)
(5-36) Lyc=	0.7+ (3.6-6	$(0.7)e^{-n^{2}(z_{3},z_{4})}$	= 0.97
, ,		•	·
(5-35) Fyc= =	(2) V,2 (421)	(25,2) 0.97	Sin O
	0291 V22		page of

CHESAPEAKE DIVISION Naval Facilities Engineering Command NDW DISCIPLINE	PROJECT: Station: Contract:
Calcs made by: date: Calcs ck'd by: date:	Calculations for: "Lateretie"
Longitudiril Currect Look (S-41) Fxform = = 1/2) Vc (33)(25.2) 0.1 cos Oc = 83.2 Vc 2 (05 Oc	
(5-44) $R_n = V_c (421) / 0.00014$ $Cxca = 0.075 / (10g R_n - 2)^2$ $S \simeq \frac{2}{3}\pi DL = 0.66 (3.14) 33 \times 421$ = 28792	
(5-42) Fx fric = -1(2) Vc2	28792 (Cxca) cos Oc
From table 13 (Pg 113) $A_R = 125$ (5-48) $A_{TPP} = 421 (33)$ (5-47) $A_P = H_{TPP} / R_3$ (6-46) $F_{XPP} = \frac{1}{2}(2)1$	/125 = 111.1 e = 132.6

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#### APPENDIX B. FORCE CALCULATIONS FOR DD 963

DM - 26.5 "Fleet Moorings" (95%) is used in this appendix to calculate forces and moments due to wind and currents on a "Spruance" Class destroyer. Here force and moment calculations are made only in dimensionless form. A computer program is then used to make detailed calculations and to determine the corrosponding mooring forces. The approach taken in this appendix is to directly quote and use equations in the DM. DM 26.5 can be referenced for a detailed description of equations and variables.

CHESAPEAKE DIVISION Naval Facilities Engineering Command NDW DISCIPLINE Calcs made by: date: Calcs ck'd by: date:	PROJECT: Station: E S R: Contract: Calculations for:
FORCE: We DMI - 26 "SPRUANCE" CLASS DEC	TROYER DD963
Lwi = 529, B = 55, T = 18.8' (1/3 stores) L Disp = 6450 L.T. " As = 25,750 ft <sup>2</sup> Ae = 4,250 ft <sup>2</sup> Lateral Wind LOAD	Scale 1 :000.  30:0 Max Nav]
(5-12) $C_{yw} = 0.92 \left[ \left( \frac{21}{23} \right)^{2/3} \times .6 + \left( \frac{55}{22} \right)^{2/3} \times .4 \right] = 0.93$ $F_{yw} = \frac{1}{2} (.00227) V_w^2 2S,250 (0.93) f_{yw}(9)$ $= 27.8 V_w^2 f_{yw}(9) *$ *Note: coefficient value of 30.2 word.  This is conservative by 7.6%.	

17.4

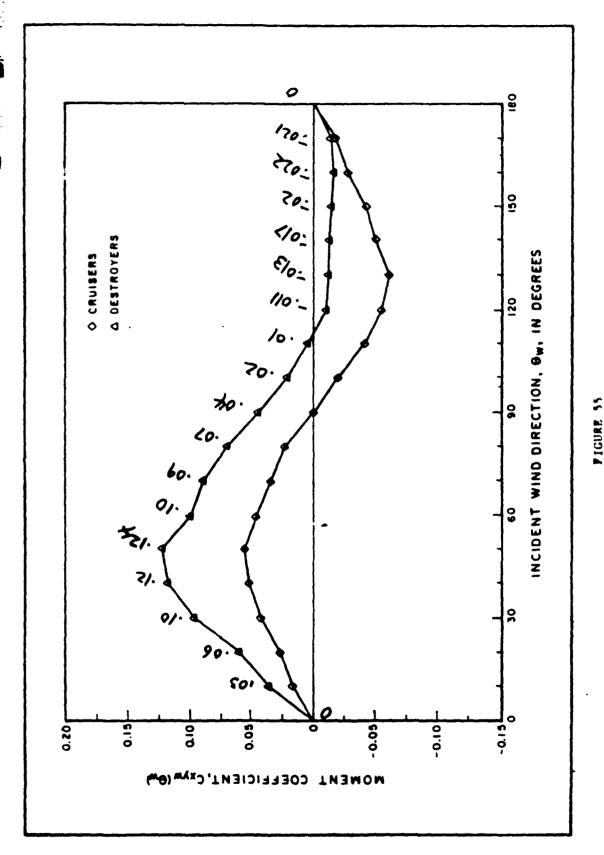
GPO 885-653

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Particular and a second property of the second particular and

CHESAPEAKE DIVISION Naval Facilities Engineering Command NDW	PROJECT:
Calcs made by: date: Calcs ck'd by: date:	E S R: Contract: Calculations for:
Long Hudina Wind Look	
Fxw = = ( .00237) Vw2	(4,350) (0.7) fxw(9)
= 3.608 VW2 Sxw	(5)
	= 15,828. Vw2 Cxyw(0)
	×55×18.8 = 0.41
from Fig 56 Upe Cycl	= 0.4 (Limiting value)
Cp = \$/1.0	
Cplu /JT = 0.41+S.	29/18.8 = 50.
from Fig 57 Cycl2 =	3, 2
fro. fig 58 K = 0.	.7
(6-36) Cyc = 0.4+(3,2-0	$-0.7(\frac{75}{18.8}-1)$
= 0,745	

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このでは、一つのことのできます。

Recommended the Soment Coefficient for Typical Naval Warships

1	KE DIVISION Engineering Command NDW	Station:
DISCIPLINE Calcs made by: _ Calcs ck'd by:	date:	E S R: Contract: Calculations for:
	Fyr = 1/21 Ve2 1520	a) (18.8) (0.745) sin Oc
	$= 7409. Vc^2$	Jin Ce
Longit	which Current load	
(5-41)	$F_{\rm X form} = -\frac{1}{2}(2) V_{\rm c}^2$ = -1034 V <sub>c</sub>	(55) (18.2) (1) 10. Gc
(5-45)	Re= Vc (529) (	05 Oc/0.000014
(5-42)	Fxsni = -1/2) Vc2	S Cxca cos Ge
(5-43)	5 = 1.7(18.8)	1529 + 35×6450/18.8 = 28915
(5-48)	ATPA = (529) (5:	5)/100 = 290.95
(5-47)	Ap = 270.95/0	1.838 = 347
(5-46)	$F_{X \text{ prop}} = -\frac{1}{2}(2)$	Ve 2 (347) (1.6) (02 Bc

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CHESAPEAKE	DIVISION	PROJECT:	
Naval Facilities Engineering Con		Station:	
DISCIPLINE			Contract:
Calcs made by:	date:		
Calcs ck'd by:	date:		
Current Yaw			
(S-49) Mxyc =	Fyc ( ec Lwc)	529	
			page of

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### APPENDIX C. BUOY SURVIVABILITY

This appendix addresses the ability of the buoy to survive various events.

CHESAPEAKE DIVISION	ON PROJECT: St. Croix Mooring
Maval Facilities Engineering Command N DISCIPLINE	DW Station: Contract:
Calcs made by: W. See(19 date:12/13 Calcs ck'd by: date:	Calculations for: Buoy Survivability

What can go wrong with the mooring when a Ship is not moored?

### Accidents

U

s

9

Little dange to the mooring or a vessel is expected if a vessel accidently runs into the mooring. The busy is "soft" and run chain covered with a protective tube. Therefore a ship or small boat will bounce of the busy. Submarine should avoid getting propeters too close to the rises. Submarine propeted design is unknown by the author. However, problems are possible if the propeter gets too close to the rises.

## Vandalism/Sabotage

Any determined group of individuals could sniously clamage the mooring with high explaines or high temperature touches. Any mooring would have similar vulnerability. A large amount of reserve buoyances is provided, so if ever a large portion (say 25%) of the buoy were removed, the buoy would still support the vises. If a section were verroved on one side, then the buoy would list and would be more difficult to moor to the busy.

page \_\_\_ of \_\_

CHESAPEAKE DIVISION	PROJECT: St. Croix Mooring
Naval Facilities Engineering Command NDW	Station:
DISCIPLINE	E S R: Contract:
Calcs made by: W. Seelig date:/2/13/84	Calculations for: Buoy Survivability
Calcs ck'd by: date:	
Extreme Environmental For	res
What happens if the hits the mooring?	largest nave possible
<u>Soln</u> :	SWL Busy Dia=10.
Hman = 0.78d	Riem Dia=3°.
=0.78(55)=42.9'	Bottom
T = 13 Sec	
will be complex and beyond	between moorning and wave I the scope of this report. iit assuming the the buoy
Riser	*
Shore Protection Manna	# Fg (7-36) (SAM)
Fd = Co = pg	DHZKom
From SPM Fig. 7-4	7
K Dm = 0.	4 page <u>2</u> of

\* US Army Corps of Engineers, CERC, 1977.

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CHESAPEAKE DIVISION Naval Facilities Engineering Command NDW DISCIPLINE	PROJECT: St. Croix Mooring  Station:  E S R: Contract:
Calcs made by: W. Seelig date: 12/12/84 Calcs ck'd by: date:	Calculations for: Busy Survivolity
From SPM Fig 7-62	
$C_0 = 0.7$	
	32.2) (3)(42.9)2(0.4)
= 48,900 165	
Buoy	
SPM En (7-25)	
$F_0 = \int_{h_1}^{h_2} f_0 dz$	e ≅ h so
SPN1 EQ (7-18)	
fo= Co≥61	Julul
Fo= h Co to	Dulul
SPM Eq (2-13)	
U= # at Cosh Cos	(SH(Z+d)/T) (OS(SLIN - SHE

page <u>3</u> of

# PROJECT: St. CTOIX MOOVING DIVISION CHESAPEAKE **Naval Facilities Engineering Command** NDW Station: \_ E S R: \_\_\_\_ Calcs made by: W. Seelij date: 12/13/84 Calculations for: Bury Survivability Calcs ck'd by: \_\_\_\_ at Surface Umax = HgT (1.0) (1.0) From SDM $\frac{d}{ds} = \frac{d}{5.12(T)^2} = \frac{55}{5.2(13)^2} = 0.06$ from SPM, Volume III $\frac{d}{1} = 0.104$ : L = d = 55 0104 = 528.8 feet : Umox = 42.9 (32.2)(13) = 16.97 fps $F_0 = 6 (0.7) \frac{1}{2} (2) (10.0) (11.97)^2$

page # of \_

CHESAPEAKE DIVISION	PROJECT: St. Croix Maring
Naval Facilities Engineering Command NDW	Station:
( IIINGIPI INF	l = a =
Calcs made by: W. Seelig date: 14/3/84	Calculations for: Bhay Survine bility
Calcs ck'd by: date:	Calculations for Date 300 Marine 11179

For a totally Stiff Strutuo the maximum drag force would be:

Since the mooring buoy will surly move some Under wave action, it is believed the actual wave free well be much less than 61 kips. For a Class "A" mooring good to 100 kips working load the mooring will survive any anticipated have action.

9

Submernee of the buoy is not anticipated to cause any problems became the buoy is "Soft" and can flex under pressure.

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#### APPENDIX D. CATHODIC PROTECTION FOR CHAIN

The chain cathodic protection design developed for use at Diego Garcia is also specified for this mooring design.

1-anode

1b. zinc anode.

### TAB A TO APPENDIX V TO ANNEX B SACRIFICIAL ZINC ANODE ATTACHMENT DETAIL

<u>₹</u> per

improved plow MIL-A-18001 zinc 1" sch. 40 core nominal dimensions 9" x wire rope 1/2" preformed IWRC equired per anode. wire rope.

improved clamps/U-bolts. clips. equired every five links. 3/4" preformed IWRC rope required per shot. 1/2" pipe

Four

required per anode. wire rope. wire

Stud link chain, 1 3/4" wire diameter.

3/4"

next

See detailed materials list

₹

From "Diego Garcia Fleet Moorings Installation", Project Execution Plan, OPORDER 6-80,

FPO-1, CHESNAVFACENGCOM, 1 Nov 1980.

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